

AN OVERWIEW AND ANALYSIS OF DEPENDECIES FOR DETERMINING THE SATURATION PRESSURE OF WATER VAPORS

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Abstract: This paper reviews, describes and analyzes the accuracy of 24 dependencies for determining the partial pressure of saturated water vapor. An important indicator of this process is the partial pressure of water vapor in the air, and its maximum value is called saturated water vapor pressure or water vapor saturation pressure, or partial saturated water vapor pressure. The assessment is made against the accepted dependency of Hardy-Wexler. Conclusions and recommendations for simple and highly accurate dependencies $p_s = f(t)$ were made.

Keywords: partial saturation pressure of water vapor - p_s ; accuracy of saturation pressure determination; dependencies for determining p_s .

1. INTRODUCTION

In order to reach a state of complete saturation, the air must absorb a certain amount of water vapor, which depends on the temperature and the total pressure. An important indicator of this process is the partial pressure of water vapor in the air, and its maximum value is called *saturated water vapor pressure* (or water vapor saturation pressure, or partial saturated water vapor pressure). It is referred to in various sources as - p_s , $p_{H\Pi}$, p_{W} , e_s or others notation.

The general type of dependence $p_s(t)$ is "exponential" - i.e. as the temperature increases, the saturation pressure increases. Figure 1 shows, in principle, this dependence on temperatures in the range $t = 0 \dots 100^{\circ}C$.



Figure 1. Water vapor saturation pressure as a function of temperature $p_s = f(t)$

Knowledge of this physical characteristic of humid air is important and necessary because it determines the nature and processes of climate and refrigeration, because it is related to the comfortable, meteorological and biological conditions of human life [1], [2].



Various dependencies (approximations) have been published to calculate saturated water vapor pressure. These dependencies are of varying complexity and accuracy [10], [12, 13]. The purpose of this paper is to review, describe the various dependencies for determining the partial pressure of saturated water vapor, to analyze and evaluate the accuracy of the various dependencies.

2. OVERVIEW OF THE BASIC DEPENDENCES FOR DETERMINING THE SESSION PRESSURE P_{S}

The reasons for having so many studies and proposals for different dependencies describing the relationship between saturated water vapor pressure ps and temperature are both the importance of the question and the desire to achieve the highest possible accuracy in calculating ps at the relative simplicity of describing the analytical dependence.

Add to this the fact that, over time, with the development of technology, the accuracy of measurements of this physical characteristic - p_s , has improved, which has necessitated a change and updating of the descriptive dependencies [3], [5], [7], [8]. There are various, developed and improved over time International temperature scales - ITS-68, IPTS-68, ITS-90. Legislators in this field are many international and technical organizations such as ASHRAE (American Society of Heating, Refrigerating and Air-Conditioning Engineers) [4], [6], [9], WMO (World Meteorological Organization) [11] and others.

Out of the many dependencies studied - $p_s(t)$, the work has been summarized and analyzed 24. They are summarized and given in Table 1, citing them based on their number or author. They are grouped by attribute - a community describing mathematical dependence. It can be summarized that the descriptive analytic dependencies used are of several types:

A. Indicative functions with the base "e" - known as "Magnus - formulas" (No. 1-5) and a generalized mathematical description:

$$p_s = c. e^{\frac{a.t}{b+t}} \tag{1}$$

B. Other types of indicator functions with base "e" (No. 6-9) and summarized mathematical description:

$$p_s = c. e^{\frac{a.t+b}{c+d.t}}$$
(2)

$$p_s = e^{a + \frac{b}{T} + c.lnT + d.T} \tag{3}$$

$$p_s = d. e^{a+b.t+c.t.t.\frac{t}{T}}$$
(4)

C. Indicative functions with basis "10" (No. 10-14) and summarized mathematical description:

$$p_s = a. 10. e^{b \cdot \frac{t}{(c+t)}} \tag{5}$$

$$p_s = a.10. e^{\frac{b+c.t}{d+t}} \tag{6}$$

D. Indicative functions with bases "e" and "10" and complex exponential polynomials (No. 15-20), with a generalized mathematical description:

$$p_{s} = exp\left(\sum_{i=1}^{6} a_{i} \cdot T_{i}^{i-2} + a_{7} \cdot lnT\right)$$
(7)

E. Other functions - polynomials indicative (No. 21-24). **IRTTE** Vol. 7, No. 4, 2019. ISSN 1314-8788 (print), ISSN 1314-8796 (online), doi: 10.15547/artte.2019.04.007



In all generalized mathematical dependences -a, b, c, d – coefficients.

Table	e 1. Main de	pendencies for	determining th	ne saturation va	apor	pressure	ps

N⁰	Addiction - Content	Conditions	Authors				
A. Indicative functions with "e" basis - Magnus formulas							
1	$n = 61121$ $\alpha m [17, 504, t/(t+2412)]$	[Dol	GOST;				
1.	$p_{\rm s} = 011,21$. $\exp[17,504.17(1+241,2)]$	[Fa]	Bogoslovski				
2.	$p_s = 611,21 \cdot \exp[17,27 \cdot t/(t+237,3)]$	[Pa]	Tetens-1				
З.	$p_{s} = 610,94 \cdot exp[17,625 \cdot t/(t+243,04)]$	[Pa]	August-Roshe				
4	$n_{\rm c} = 611.21$ exp[17.502 t //240.97 + t)]	[Pa]	Buck-1;				
	ρ _s = 0+1,2 + : 0,0[+1,002.t7](2+0,01+17)]	[[G]	Romanov-1				
5.	$p_s = 611,2 \cdot exp[17,62.t/(243,12+t)]$	[Pa]	Magnus-2				
B. Other types of indicator functions with the basis "e"							
6.	$p_{\rm s} = \exp(16,57.t - 115,72)/(233,77+0,997.t)$	(t = 083 ⁰ C), [kPa]	AVOK- Tarabanov				
	$n_{\rm e} = \exp(54.1945 - 6644.48/T - 4.115 \ln(T) -$	0	raiaballov				
7.	-0,00134848.T)	$t = -6060^{\circ}C, [Pa]$	Hardy				
8.	$p_s = 611,21 \cdot exp \{(18,678 - t/234,5) \cdot [t/(257,14 + t)]\}$	[Pa]	Buck – 2				
9.	$p_{\rm s} = 611,21.\exp\left[(19,846 - 8,97.10^{-3}.t + 1,248.10^{-9}.t^{-2}).t/T\right]$	[Pa]	Romanov-2				
C. Indicative functions with base "10"							
10	$lg p_s = (156+8, 12.t) / (236+t)$	Imm Hal IPal	Filney,				
	$p_{\rm s} = 133,3224.10^{(10000,12.1)(230+1)}$	[Staroverov				
11.	$p_{\rm s} = 10^{110,1902+1730,057} (233,420+7)$	[Pa]	Antoan				
12.	$p_{\rm s} = 611 \cdot 10^{7.45 \cdot 17(237.5 + 1)}$	[Pa]	Magnus-1				
13.	$p_{\rm s} = 610,7.10^{-7,000.17}$	[Pa]	Alduchov				
14.	$p_{\rm s} = 611 \cdot 10^{-7, 5 \cdot 17 + (257, 5 \cdot 17)}$	[Pa]	Tetens-2				
	D. Indicative functions with "e" and "10" bases and complex exponential polynomials						
15.	$ln p_{s} = -5,8002206.10^{\circ}/T + 1,3914993 - 4,8640239.10^{\circ}.T +$	T = 273473K	Hyland - Wexler				
	$+4,1764768.10^{\circ}.1^{\circ}-1,4452093.10^{\circ}.1^{\circ}+6,5459673.10^{\circ}$	$(t = 0200^{\circ}C), [Pa]$	ASHRAE				
10	$ln p_s = -2991, 2729.1^{-2} - 6017, 0128.1^{-1} + 18, 87643854 - 0.00005170 T = -10, 73000001, 10, 55, 72^{-2} = 0.00001, 10, 50, 10, 73000000, 10, 50, 10, 73000000, 10, 50, 10, 73000000, 10, 50, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 73000000, 10, 75000000, 10, 75000000, 10, 75000000, 10, 75000000, 10, 75000000, 10, 75000000, 10, 75000000, 10, 750000000, 10, 750000000, 10, 750000000, 10, 7500000000000000000000000000000000000$	(D. 1					
16.	$-0,02835472.1 + 1,7838301.10^{-1.1} - 8,4150417.10^{-1.1} + 1,7838301.10^{-13} = -8,4150417.10^{-1.1} + 1,7838301.10^{-1.1} = -8,4150417.10^{-1.1} = -8,4150717.10^{-1.1} = -8,4150717.10^{-1.1} = -8,415071$	[Pa]	Wexler A.				
	+4,4412543.10 .1 $+2,858487.101$						
17.	$111 p_s = -6096,9363.1 + 10,03635794 - 2,771793.10 .1 + 1.673952.10 -5 . T2 + 2.433502 . InT$	[hPa], ITS-90	Sonntag- Heinze				
	$ln p_s = -2836.5744.T^{-2} - 6028.076559 .T^{-1} + 19.5426361 -$						
18.	-2,737830188. 10 ⁻² .T + 1,6261698.10 ⁻⁵ .T ² +	[Pa], ITS-90	Hardy - Wexler				
	+7,0229056.10 ⁻¹⁰ .T ³ –1,8680009.10 ⁻¹³ .T ⁴ + 2,7150305.InT		-				
	$lg p_s = -7,90298(373,16/T - 1) + 5,02808. \ lg(373,16/T) + 6,02808. \ lg(373,16/T) + 6,02808.$	[hPa]	Coff_				
19.	$+ 1,3816.10^{-7}.[10^{-11,344.(1-1/3/3,16)} - 1] + 8,1328.10^{-3}.[10^{-3,49149.(3/3,16)} - 1]$	[រារ ង]	Gratch -1				
	^{1 – 1)} - 1] + lg 1013,246		Grateri - I				
20.	$lg p_{s} = 10,79574.(1 - 273,16/T) - 5,028.lg(T/273,16) + 476055$	[hPa]	GOST				
	$+1,50475.10^{-4}.[1-10^{-6,290.(17/273,10-7)}]+0,42873.10^{-3}.[10^{-4,70903.(17/273,10-7)}]$	[in d]	(Goff –				
	- 1] + 0,78614		Gratch -2)				
E. Other functions - polynomials, exponents							
21.	$p_{\rm s} = \exp(77,34 - 7235/T - 8,2 \cdot \ln T + 0,005711 \cdot T)$	[Pa]	Uni Helsinki				
22.	$p_s = 271,98.(0,01.T - 1,623)^\circ$	<i>t</i> = 060°C [Pa]	Sprav.OVK				
23.	$p_s = 479 + (11,52 + 1,62.t)^2$	t > 0 [Pa]	Russian				
24.	p _s = 133,3224.exp(20,386 – 5132 / T)	[Pa]	Wikipedia				

3. AN ANALYSIS OF THE ACCURACY OF THE DIFFERENT DEPENDENCES ON THE VACATION PRESSURE

The accuracy of all these dependencies is estimated by the deviation (relative error) $\delta = f(T)$ of the saturation pressure p_s from the accepted reference p_s et for different approximations and is shown in the graphs in Figure 2. A relative error is defined as:

$$\delta = \frac{p_s - p_{s\,et}}{p_{s\,et}} \tag{8}$$



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18. Hardy – Wexler dependency is assumed to be the baseline reference for which the accuracy assessment is made.







Figure 2 c. Indicative functions based on "10" (10-14)



Figure 2 b. Other types of indicative functions with an "e" basis (6-9)



Figure 2 d. Other functions - polynomials indicative (21-24)



Figure 2 e. Indicative functions with bases "e" and "10" and complex indicator polynomials (15-20)

Figure 2. Saturation pressure deviation $\delta = f(T)$ with respect to base dependency "18.Hardy-Wexler"



The analysis of the results thus processed shows:

- among the dependences A (No. 1-5), the formula *"2.Tetens-1"* up to t <600C shows relatively good accuracy δ <± 0.1%;
- the dependencies of group E (No. 21-24) are the most inaccurate for them the deviations are in the range of δ <± 3%;
- in the second group of dependencies B (No. 6-9) the formulas of "9.Romanov-2" δ <± 0.01% and "8.Buck-2" δ <± 0.05% stand out with their high accuracy.;
- among the common dependencies of group C (№10... 14) high dependence in the working range has the dependence *"14.Tetens-2"* - δ <± 0.1%, as well as "10.Filney" and "11.Antoan";
- the most accurate are the most complex analytical dependencies of group D (No. 15-20), among which the basic dependence is considered *"18.Hardy-Wexler*". For them the deviations are small δ <- 0,1%.

It should be specified that the saturation pressure of water vapor in a multi-component system such as air (also referred to as effective effective saturation pressure - p_s) generally depends on both temperature and total pressure or:

$$p'_{s} = f(t, p_{a}) = k(p). p_{s}$$
 (9)

where k(p) is a pressure correction function.

This correction is within (0.45... 0.5)% and is often not taken into account when determining the saturation pressure. The correction function can be determined depending on the type:

$$k(p) = 1,0016 + 3,1510^{-6}p - 0,074p^{-1}$$
⁽¹⁰⁾

where *p* is the total pressure, [hPa].

Figure 3 shows the pressure-correcting pressure function k(p) = f(p) determined by (10) and WMO data.



Figure 3. Pressure - dependent pressure correction function k(p) = f(p)



4. CONCLUSION

In this work, 24 dependencies are investigated to determine the saturation pressure of water vapor ps.

An analysis of the dependencies and an assessment of their accuracy with respect to the base dependence of 18. Hardy-Wexler was performed. Recommendations for the use of approximation dependencies are determined by:

- the tasks assigned;
- the accuracy required;
- time and technical possibilities for using different dependencies;
- range of change in air temperature;
- influence of change in atmospheric pressure.

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